

Integrating simulation modelling for sustainable, human-centred Industry 5.0: ESG-based evaluation in collaborative workplaces

Ojstersek, R.^{a,*}, Javernik, A.^a, Buchmeister, B.^a

^aUniversity of Maribor, Faculty of Mechanical Engineering, Maribor, Slovenia

ABSTRACT

This research explores the role of simulation modelling in the development of human-centred, sustainable manufacturing processes in the context of Industry 5.0. We analyse collaborative workplaces where humans and collaborative robots (CR) work together, emphasizing the environmental, social, and governance (ESG) criteria. The research work focuses on how personalized CR parameters and optimized work environments contribute to improved productivity, well-being, and sustainability. Through simulations, the paper evaluates the operational efficiency of both manual assembly and human-robot collaborative (HRC) setups, providing insight into the economic, environmental, and social impacts of Industry 5.0 manufacturing systems. The results show significant improvements in sustainability, productivity, and worker well-being achieved through adaptive CR integration and ESG-driven engineering practices.

ARTICLE INFO

Keywords:

Human-Centred manufacturing;
Simulation modelling;
Sustainability – ESG;
Industry 5.0;
Collaborative workplace;
Human-robot interaction;
Assembly process

*Corresponding author:

robert.ojstersek@um.si
(Ojstersek, R.)

Article history:

Received 23 August 2024
Revised 28 November 2024
Accepted 5 December 2024



Content from this work may be used under the terms of the Creative Commons Attribution 4.0 International License (CC BY 4.0). Any further distribution of this work must maintain attribution to the author(s) and the title of the work, journal citation and DOI.

References

- [1] Adel, A. (2022). Future of industry 5.0 in society: Human-centric solutions, challenges and prospective research areas, *Journal of Cloud Computing*, Vol. 11, Article No. 40, doi: [10.1186/S13677-022-00314-5](https://doi.org/10.1186/S13677-022-00314-5).
- [2] Ojstersek, R., Javernik, A., Buchmeister, B. (2022). Importance of sustainable collaborative workplaces-simulation modelling approach, *International Journal of Simulation Modelling*, Vol. 21, No. 4, 627-638, doi: [10.2507/IJSIMM21-4-623](https://doi.org/10.2507/IJSIMM21-4-623).
- [3] Mourtzis, D., Angelopoulos, J., Panopoulos, N. (2022). A literature review of the challenges and opportunities of the transition from Industry 4.0 to Society 5.0, *Energies*, Vol. 15, No. 17, Article No. 6276, doi: [10.3390/EN15176276](https://doi.org/10.3390/EN15176276).
- [4] Montini, E., Cutrona, V., Dell'Oca, S., Bettoni, A., Landolfi, G., Rocco, P., Carpanzano, E. (2024). An industrial human-robot collaboration case study for workers' well-being, *Procedia CIRP*, Vol. 130, 924-929, doi: [10.1016/J.PROCIR.2024.10.186](https://doi.org/10.1016/J.PROCIR.2024.10.186).
- [5] Calzavara, M., Faccio, M., Granata, I., Trevisani, A. (2024). Achieving productivity and operator well-being: A dynamic task allocation strategy for collaborative assembly systems in Industry 5.0, *The International Journal of Advanced Manufacturing Technology*, Vol. 134, 3201-3216, doi: [10.1007/S00170-024-14302-3/FIGURES/17](https://doi.org/10.1007/S00170-024-14302-3/FIGURES/17).
- [6] Tripathi, M.A., Sawant, P.D., Kaur, H., Almhairah, M.S., Chandel, P.S., Balakumar, A. (2024). Human-robot collaboration in the workplace: Assessing the impact on employee well-being and productivity, In: *Proceedings of 2024*

- Third International Conference on Intelligent Techniques in Control, Optimization and Signal Processing*, Krishnan-koil, India, 1-7, doi: [10.1109/INCOS59338.2024.10527509](https://doi.org/10.1109/INCOS59338.2024.10527509).
- [7] Bouaziz, N., Bettayeb, B., Sahnoun, M., Yassine, A. (2024). Incorporating uncertain human behavior in production scheduling for enhanced productivity in Industry 5.0 context, *International Journal of Production Economics*, Vol. 274, Article No. 109311, doi: [10.1016/J.IJPE.2024.109311](https://doi.org/10.1016/J.IJPE.2024.109311).
- [8] Azemi, F., Šimunović, G., Lujić, R., Tokody, D., Mulaku, L. (2023). Green manufacturing and environmental sustainability manufacturing in Kosovo's small and middle enterprises, barriers to implementation, *Tehnički Vjesnik – Technical Gazette*, Vol. 30, No. 3, 988-992, doi: [10.17559/TV-20220528121801](https://doi.org/10.17559/TV-20220528121801).
- [9] Javernik, A., Buchmeister, B., Ojstersek, R. (2023). The NASA-TLX approach to understand workers workload in human-robot collaboration, *International Journal of Simulation Modelling*, Vol. 22, No. 4, 574-585, doi: [10.2507/IJSIMM22-4-658](https://doi.org/10.2507/IJSIMM22-4-658).
- [10] Asif, M., Searcy, C., Castka, P. (2023). ESG and Industry 5.0: The role of technologies in enhancing ESG disclosure, *Technological Forecasting and Social Change*, Vol. 195, Article No. 122806, doi: [10.1016/J.TECHFORE.2023.122806](https://doi.org/10.1016/J.TECHFORE.2023.122806).
- [11] Wang, H., Jiao, S., Bu, K., Wang, Y., Wang, Y. (2023). Digital transformation and manufacturing companies' ESG responsibility performance, *Finance Research Letters*, Vol. 58, Part B, Article No. 104370, doi: [10.1016/J.FRL.2023.104370](https://doi.org/10.1016/J.FRL.2023.104370).
- [12] Liu, L., Schoen, A.J., Henrichs, C., Li, J., Mutlu, B., Zhang, Y., Radwin, R.G. (2024). Human robot collaboration for enhancing work activities, *Human Factors: The Journal of the Human Factors and Ergonomics Society*, Vol. 66, No. 1, 158-179, doi: [10.1177/00187208221077722](https://doi.org/10.1177/00187208221077722).
- [13] Gültekin, A., Diri, S., Becerikli, Y. (2023). Simplified and smoothed rapidly-exploring random tree algorithm for robot path planning, *Tehnički Vjesnik – Technical Gazette*, Vol. 30, No. 3, 891-898, doi: [10.17559/TV-20221015080721](https://doi.org/10.17559/TV-20221015080721).
- [14] Javernik, A., Buchmeister, B., Ojstersek, R. (2022). Impact of Cobot parameters on the worker productivity: Optimization challenge, *Advances in Production Engineering & Management*, Vol. 17, No. 4, 494-504, doi: [10.14743/apem2022.4.451](https://doi.org/10.14743/apem2022.4.451).
- [15] Matheson, E., Minto, R., Zampieri, E.G.G., Faccio, M., Rosati, G. (2019). Human-robot collaboration in manufacturing applications: A review, *Robotics*, Vol. 8, No. 4, Article No. 100, doi: [10.3390/ROBOTICS8040100](https://doi.org/10.3390/ROBOTICS8040100).
- [16] Petzoldt, C., Harms, M., Freitag, M. (2023). Review of task allocation for human-robot collaboration in assembly, *International Journal of Computer Integrated Manufacturing*, Vol. 36, No. 11, 1675-1715, doi: [10.1080/0951192X.2023.2204467](https://doi.org/10.1080/0951192X.2023.2204467).
- [17] Othman, U., Yang, E. (2023). Human-robot collaborations in smart manufacturing environments: Review and outlook, *Sensors*, Vol. 23, No. 12, Article No. 5663, doi: [10.3390/S23125663](https://doi.org/10.3390/S23125663).
- [18] Murali, P.K., Darvish, K., Mastrogiovanni, F. (2020). Deployment and evaluation of a flexible human-robot collaboration model based on AND/OR graphs in a manufacturing environment, *Intelligent Service Robotics*, Vol. 13, No. 4, 439-457, doi: [10.1007/S11370-020-00332-9](https://doi.org/10.1007/S11370-020-00332-9).
- [19] Lorenzini, M., Lagomarsino, M., Fortini, L., Gholami, S., Ajoudani, A. (2023). Ergonomic human-robot collaboration in industry: A review, *Frontiers*, Vol. 9, Article No. 813907, doi: [10.3389/FROBT.2022.813907](https://doi.org/10.3389/FROBT.2022.813907).
- [20] Panagou, S., Neumann, W.P., Fruggiero, F. (2024). A scoping review of human robot interaction research towards Industry 5.0 human-centric workplaces, *International Journal of Production Research*, Vol. 62, No. 3, 974-990, doi: [10.1080/00207543.2023.2172473](https://doi.org/10.1080/00207543.2023.2172473).
- [21] Xiao, J., Huang, K. (2024). A comprehensive review on human-robot collaboration remanufacturing towards uncertain and dynamic disassembly, *Manufacturing Review*, Vol. 11, Article No. 17, doi: [10.1051/MFREVIEW/2024015](https://doi.org/10.1051/MFREVIEW/2024015).
- [22] Šegota, S.B., Anđelić, N., Car, Z., Šercer, M. (2022). Prediction of robot grasp robustness using artificial intelligence algorithms, *Tehnički Vjesnik – Technical Gazette*, Vol. 29, No. 1, 101-107, doi: [10.17559/TV-20210204092154](https://doi.org/10.17559/TV-20210204092154).
- [23] Hopko, S., Wang, J., Mehta, R. (2022). Human factors considerations and metrics in shared space human-robot collaboration: A systematic review, *Frontiers*, Vol. 9, Article No. 799522, doi: [10.3389/FROBT.2022.799522](https://doi.org/10.3389/FROBT.2022.799522).